

Adapting Data Acquisition Strategies from Large-Scale Facilities – Or How to Dance in the Lab?

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**HUN
REN**

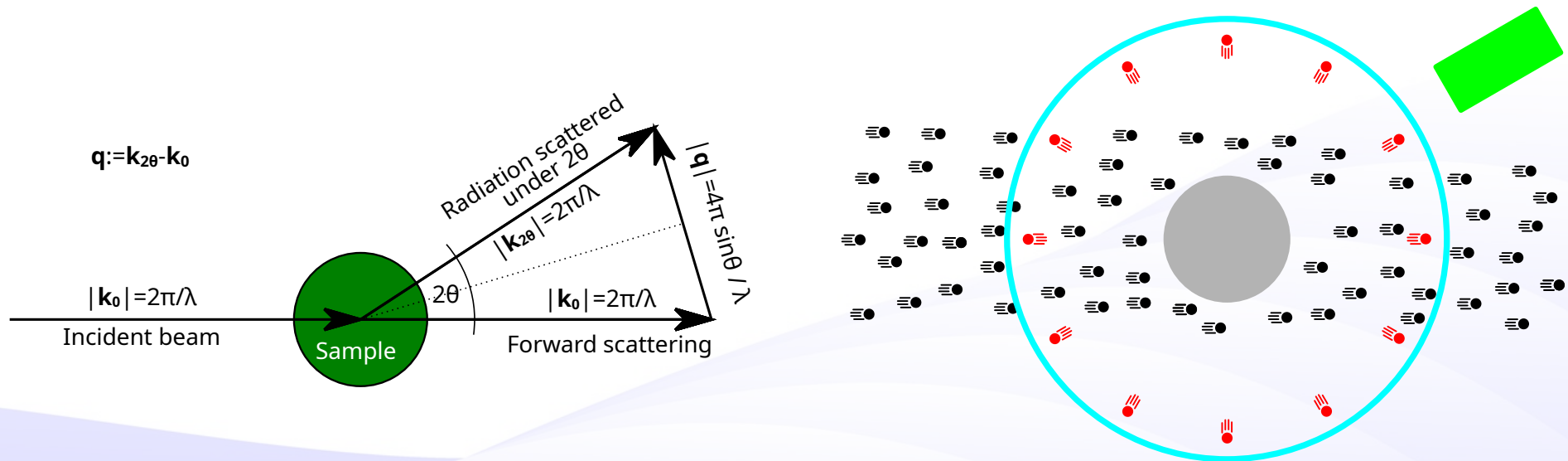


Motivation: Why do we need data acquisition strategies?

- Computerized measurements: possibilities and liabilities
 - Frequent recording of the measurand
 - Automation (sample, geometry or “environment” changes)
 - Easier storage, data is ready for reduction, interpretation...
- The requirement for reproducibility and correctness
 - Recording as many aspects of the experiment as possible (or necessary)
 - Eliminating uncontrolled parameters
 - Repeating experiments under the same conditions
- Data storage considerations
 - Safe (against data loss or corruption)
 - Secure (access control, privacy)
 - Short term / long term
 - Raw or processed data
 - Open data, FAIR principles
- “Do not reinvent the wheel!”
 - Build on already developed and proven utilities and techniques
 - Each experimental field has its own “best practices” and “publication guidelines”

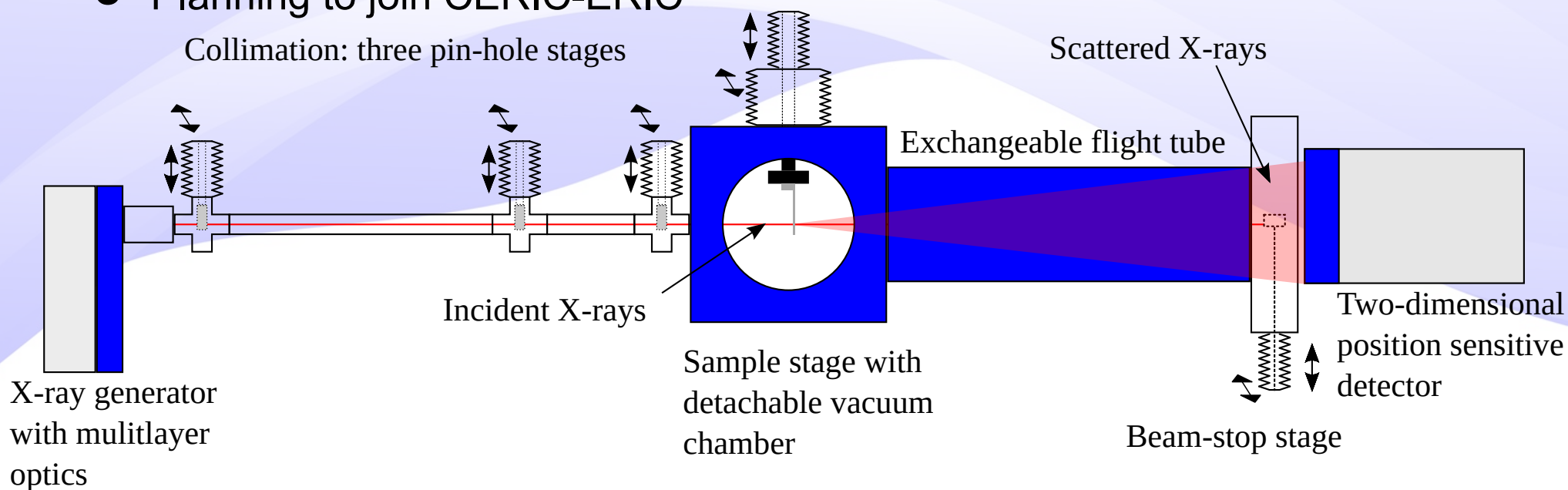
Case study: small-angle X-ray scattering

Small-angle X-ray scattering – from the experimentalist’s point of view



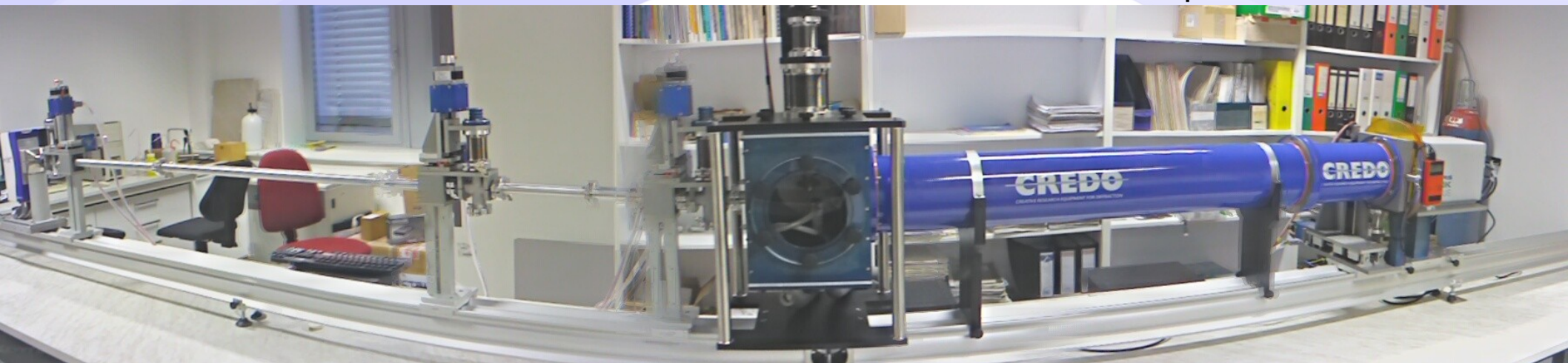
- Fixed wavelength, moderate monochromaticity ($\Delta\lambda/\lambda < 1\%$), highly parallel
- Physics: elastic scattering
- Primary data: “count rate” vs. “scattering angle”
- Instrument-independent units
 - Differential scattering cross-section (“ $d\sigma/d\Omega$ ”, $\text{cm}^2/\text{cm}^3 \times \text{sr}^{-1}$)
 - Momentum transfer (“ q ”, nm^{-1})
- Typically two-dimensional detector, scattering pattern
- Stationary geometry, data acquisition for several minutes/hours (lab), few msec (synchrotron)

- In-house built laboratory SAXS camera (→ ask me for a tour in the lab)
 - Based on synchrotron experience
- Optimized three-pin-hole collimation system
- Wide angular range from 0.02 to 30 nm⁻¹ ($q=4\pi\sin(\theta)/\lambda$)
- Extensively motorized (XY for pin-holes, sample and beam stop)
- Unique in the region
 - Only SAXS instrument in Hungary
 - Serves all researchers in-house (including other groups)
 - Access for guest researchers via a beamtime proposal system
 - Planning to join CERIC-ERIC



The CREDO hardware

- Core components
 - Source: GeniX^{3D} Cu ULD (Xenocs SA, Sassenage, France)
 - Detector: Pilatus-300k (Dectris Ltd, Baden, Switzerland) → 0.3 Mpixel
 - Stepper motor controllers (Trinamic GmbH, now Analog Devices)
 - Vacuum gauge: TPG-201 (Pfeiffer Vacuum)
 - Thermometer (SE521)
- In situ measurements
 - Thermostating water circulator (Haake Phoenix P25C)
 - Peristaltic pump (LeadFluid BT100s)
 - Sample illumination (Schott KL2500)
 - Magnetic stirrer (IKA RET control-visc)
- Other
 - Uninterruptible Power Supply (Tecnoware Evo DSP Plus)
 - Detector gas supply sensor (In-house built, Raspberry-Pi-based)
 - ...
- RS-232, RS-485, Modbus-TCP, USB HID, TMCL, and other domain-specific solutions

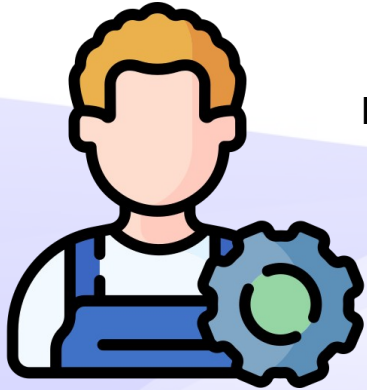




Designing a data acquisition system

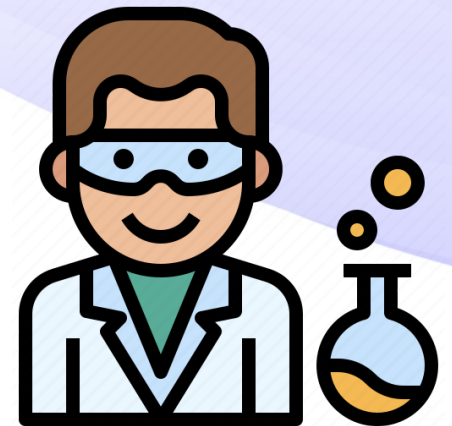
Requirements towards the control and data acquisition system

- For the developer: easy to extend
 - flexible enough to accommodate heterogeneous equipment
 - Specification always change
 - Modular: devices can be inserted and removed
 - Developing drivers for new devices should be easy
 - Build on already available solutions
 - Free software vs. paid solutions?



- For the operator / beamline scientist: highly automated, ease of use
 - Perform required background and calibrant measurements
 - Measure multiple samples in a sequence
 - Standardized procedures (data acquisition, reduction)

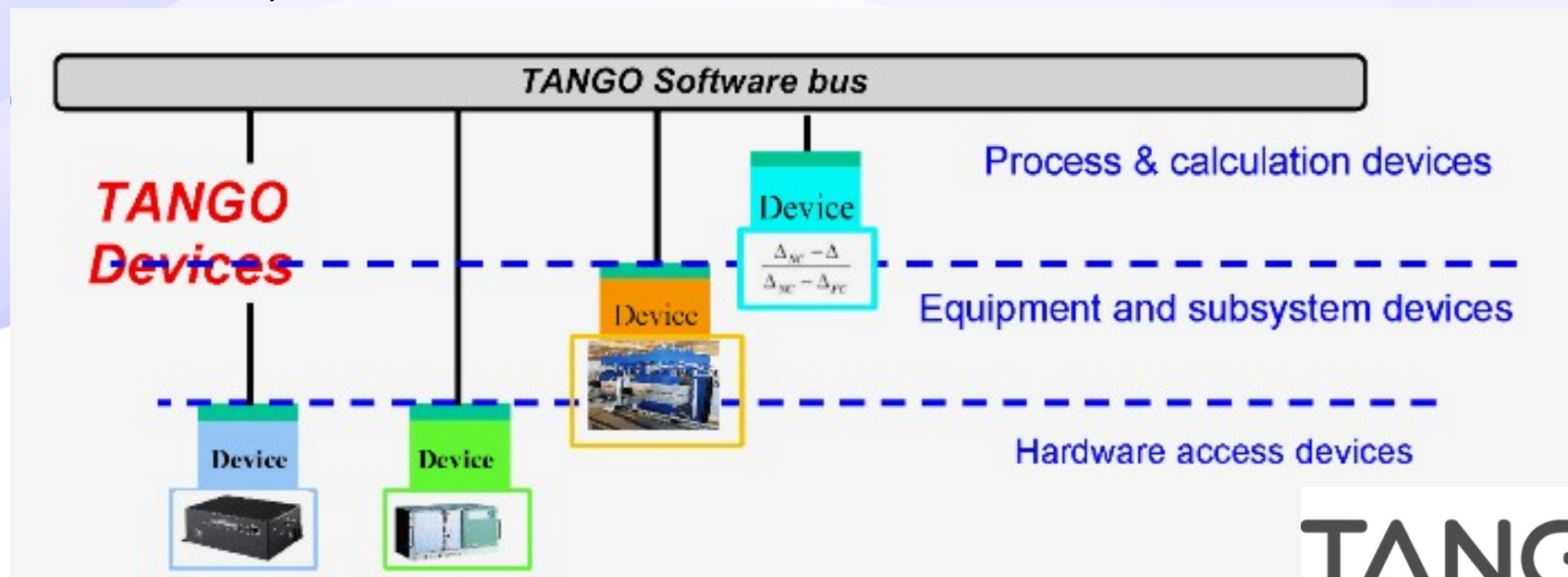
- For the casual user / guest researcher: reliable, correct
 - Control *in situ* parameters (temperature, shear, illumination, flow rate...)
 - In-process visualization and assessment of the quality of the results
 - User-friendly
 - Standards-compatible data storage
 - High throughput



The TANGO Control System

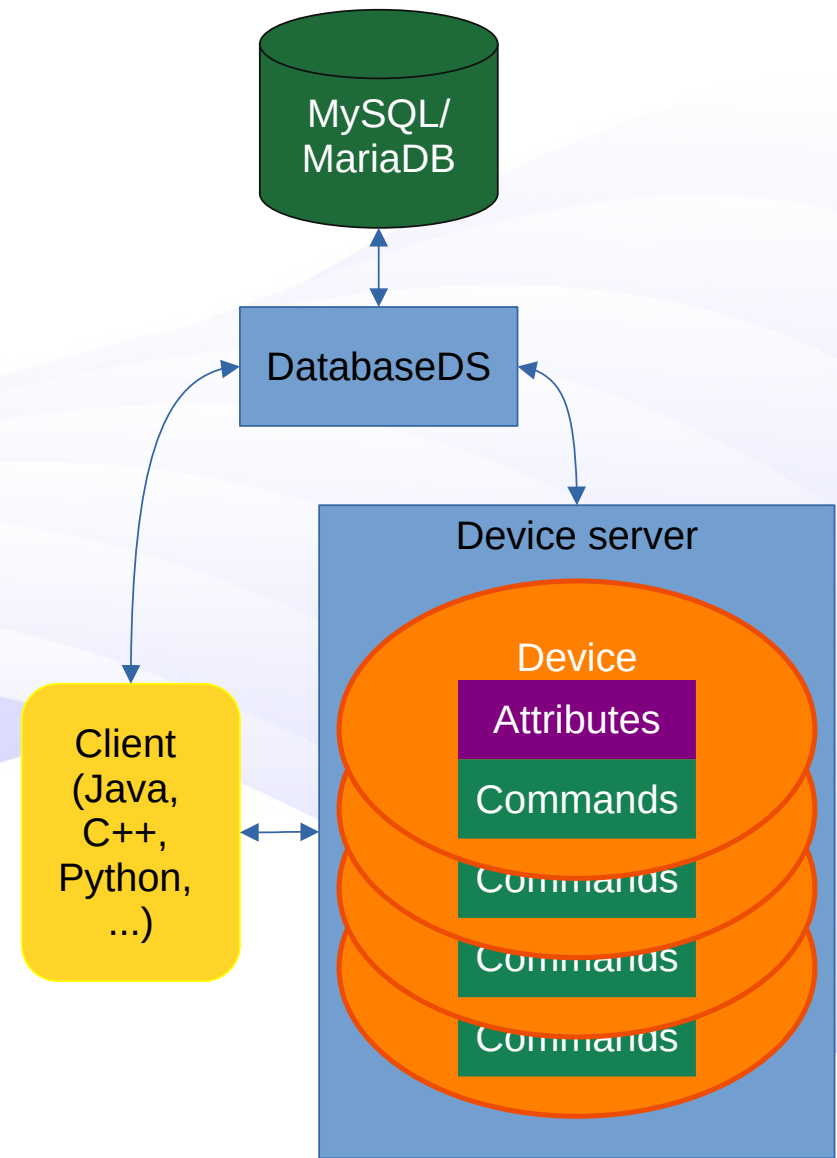
(<https://www.tango-controls.org>)

- Developed initially at ESRF (Grenoble), then by the Tango Controls Consortium: ESRF, DESY, ALBA, SOLEIL, ELETTRA, SOLARIS, ELI BEAMS, MAX-IV, FRM-II, ...
- A “software bus”: a standardized way of communication between various parts of the instrument
- Unified interface: hiding how the equipments are connected (USB, TCP/IP, RS-232...) and where (individual computers on the network)
- Distributed: devices can be attached anywhere, even relocated
- Object-oriented approach (CORBA: Common Object Request Broker Architecture™)



The Tango Architecture

- Basic unit: device
 - Device server: a program managing various devices of the same type (“device class”)
 - Not just hardware devices:
 - Algorithms (data reduction, file writer, loggers, software subsystems)
 - Meta-devices (e.g. stepper motors belonging to the same controller)
 - Interfaces (RS232, Modbus, TCP socket...): other device servers may rely on these
- Server code: C++, Java, Python
- Client code: C++, Java, Python, Matlab, Igor Pro, Labview...



The TANGO device: living inside the device server



- Name: <domain>/<family>/<member>
 - e.g., <beamline>/<equipment type>/<equipment name>
 - credo/detector/pilatus300k
 - e.g., <interface type>/<computer>/<equipment name>
 - serial/credo-pi/thermostat, motor/beamstopcontroller/bsx
- Object-oriented approach
 - Class: the type of equipment it controls (e.g. a Haake Phoenix P25C thermostat via RS-232)
 - Attributes: state variables
 - Read-only (current temperature, current motor speed)
 - Read/write (temperature set point, target motor position)
 - 0-1-2 dimensional
 - Commands (“methods” in the C++ terminology): operations that can be performed
 - e.g. open the beam shutter, start water circulation...
 - Properties: parameters and settings not expected to change
 - Hardware address of the device
 - Pipes: transferring a large amount of data

Anatomy of a TANGO device: the X-ray source of CREDO

- `credo/source/genix` (the X-ray source)
 - Properties:
 - *modbus*: `modbus/credo2/genix` (another TANGO device!)
 - Attributes:
 - *State* (common to all TANGO devices: one of ON, OFF, CLOSE, OPEN, INSERT, EXTRACT, MOVING, STANDBY, FAULT, INIT, RUNNING ALARM, DISABLE or UNKNOWN)
 - *Status* (common to all TANGO devices: a textual representation of the current state)
 - *current*: the actual current in the X-ray tube (mA)
 - *ht*: high tension of the X-ray tube (kV)
 - *vacuum_fault...*
 - ...
 - Commands:
 - *StartWarmUp*, *StopWarmUp*, *FullPower*, *GoStandby*, *PowerOff*, *ResetFaults*, ...

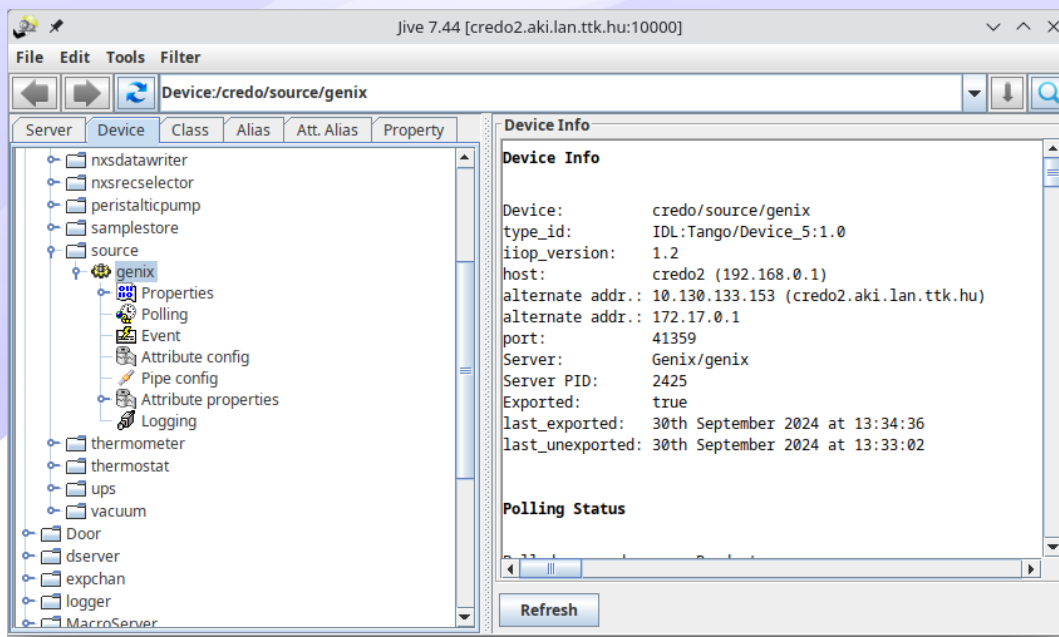
Special devices: DatabaseDS and Starter

■ DatabaseDS

- One is required for each Tango system (on a dedicated server host)
- Interface to the SQL database
- Provides name resolution: where can the device $x/y/z$ be found?
- Storing information about devices: classes, on which computer they are running, which instances, which device servers, name aliases...
- GUI: Jive

■ Starter: orchestration

- Not required but very helpful
- Typically on each computer in the Tango system where device servers are running
- Started by the OS
- Responsible for starting, stopping, restarting device servers on this computer (as defined in the database)
- GUI: Astor (*cf* ~ Piazzola)



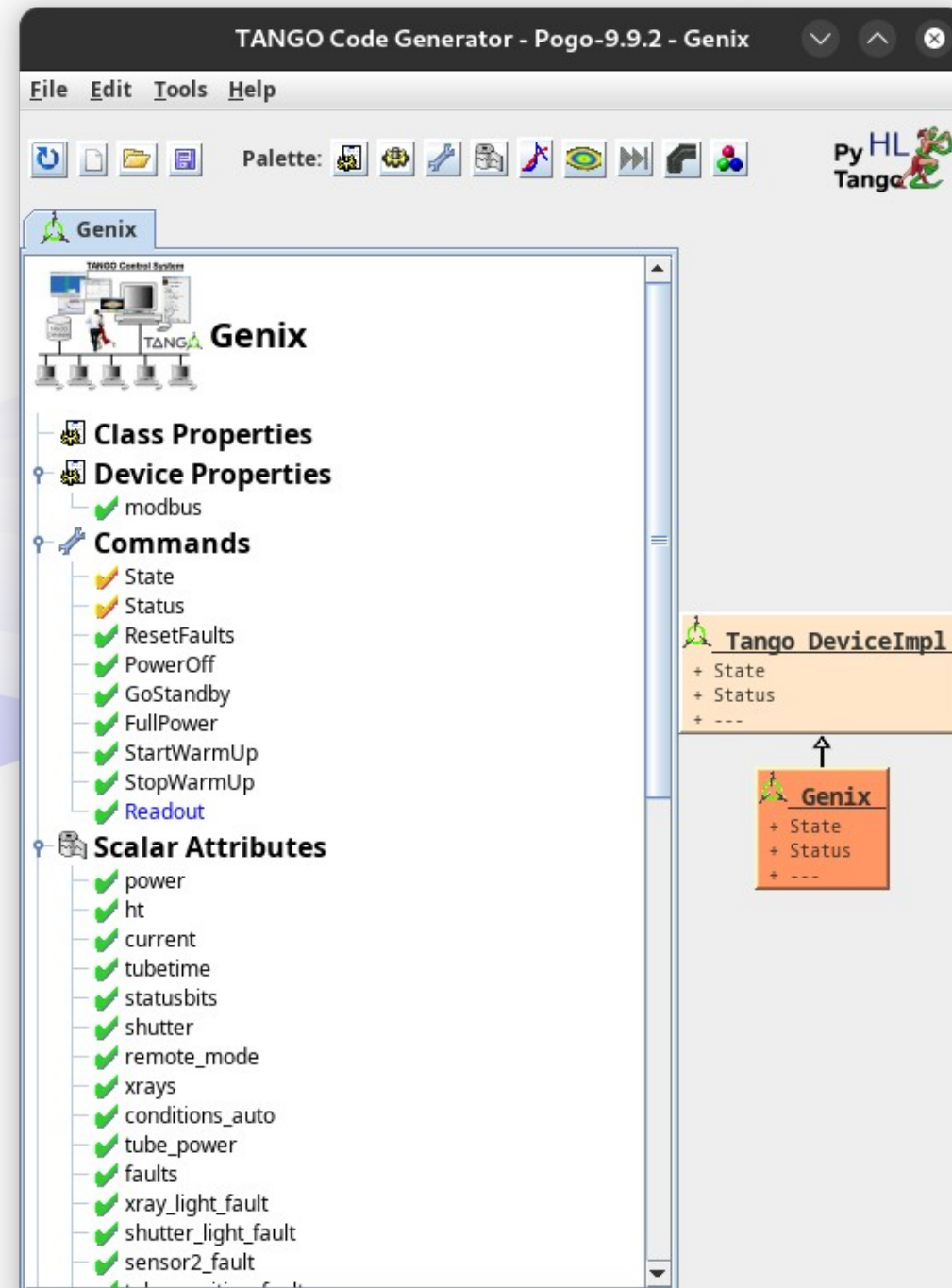
Developing Device Servers – Pogo



- Program Obviously used to Generate Objects
- Graphical user interface to define the devices
- Store the data in an XML file
- Writes skeleton code (C++, Java, Python), which can be fleshed out
- Auto-generation of documentation
- XML file can be uploaded to the Tango Classes Catalogue (<https://www.tango-controls.org/developers/dsc/>)

```
def read_shutter(self):
    # PROTECTED REGION ID(Genix.shutter_read) ENABLED START #
    """Return the shutter attribute."""
    # ...
    # Actual code to read the variable comes here
    # ...
    return self._shutter
    # PROTECTED REGION END # // Genix.shutter_read

def write_shutter(self, value):
    # PROTECTED REGION ID(Genix.shutter_write) ENABLED START #
    """Set the shutter attribute."""
    # ...
    # Actual code to write the variable comes here
    # ...
    # PROTECTED REGION END # // Genix.shutter_write
```



Python Language Bindings

- PyTango (<https://pytango.readthedocs.io/en/latest/>)
- Object-oriented approach
 - Tango attributes → data members
 - Tango commands → member functions
- Both for servers and clients
- Introspection
 - `get_attribute_list()`
 - `get_command_list()`
- Interaction with the Tango database
- ITango: improved, Tango-aware variant of Ipython

Py
Tango

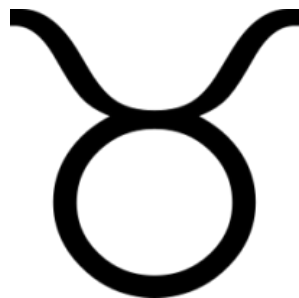


```
In [1]: from tango import DeviceProxy
In [2]: vac = DeviceProxy('credo/vacuum/tpg201')
In [3]: vac.get_attribute_list()
Out[3]: ['pressure', 'version', 'units', 'State', 'Status']
In [4]: vac.pressure
Out[4]: 0.034
In [5]: vac.Status()
Out[5]: '0.034 mbar'
In [6]: genix = DeviceProxy('credo/source/genix')
In [7]: genix.shutter
Out[7]: False
In [8]: genix.shutter = True
In [9]: genix.get_command_list()
Out[9]: ['FullPower', 'GoStandby', 'Init', 'PowerOff', 'Readout',
'ResetFaults', 'StartWarmUp', 'State', 'Status', 'StopWarmUp']
In [10]: genix.PowerOff()
```

Other Uses and Features of TANGO

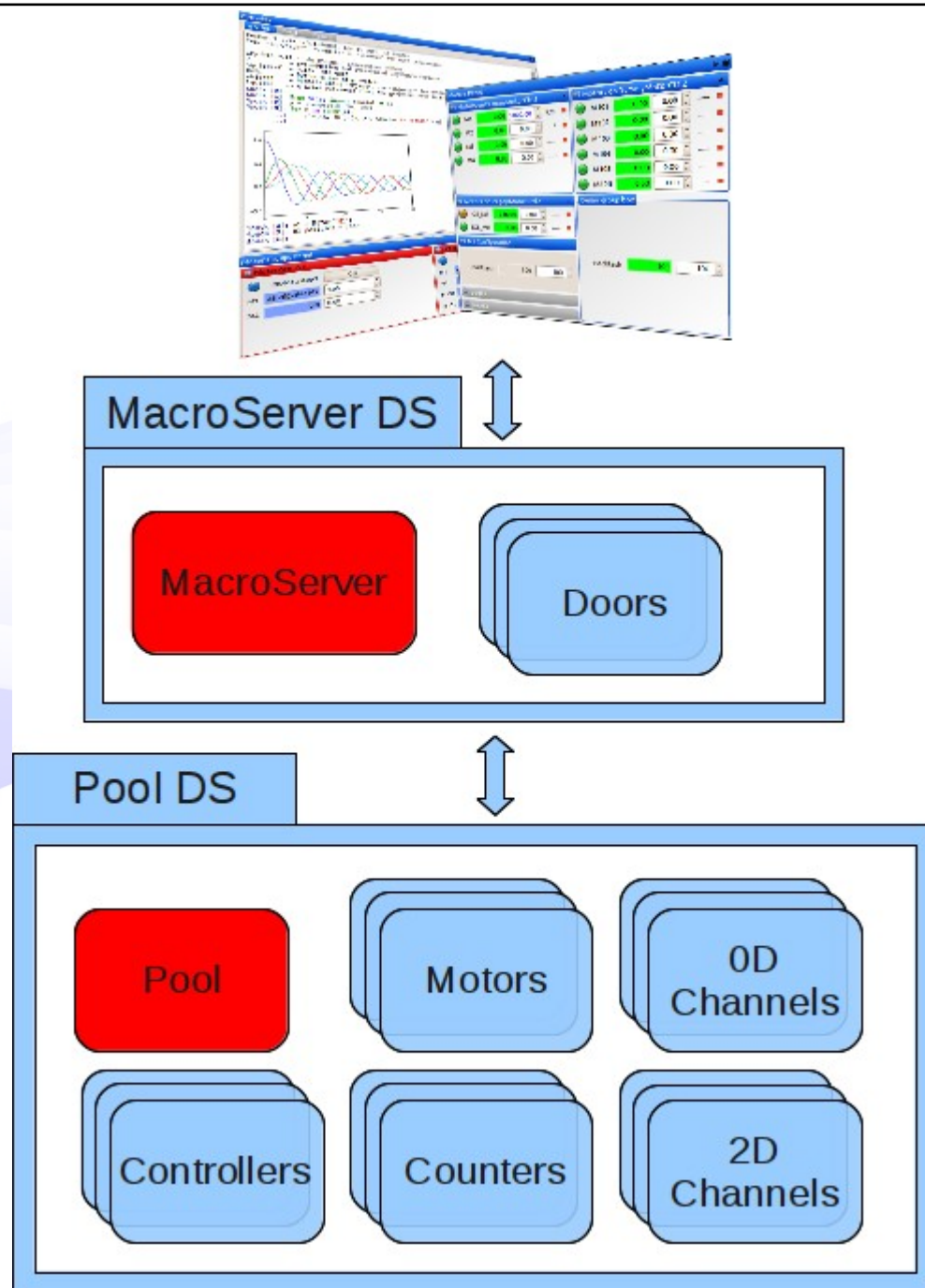
- Logging facility: messages from the device servers (errors, warnings...)
 - Java GUI: LogViewer
- Polling:
 - automatic, periodic query of attributes (state variables)
 - ... or execution of commands
- Event system
 - Client programs can subscribe to event notifications by the device servers
 - React to changes instantaneously
 - Warning and alarm events
 - Lower and upper thresholds for attribute values
- Archival of attribute values
 - either periodically,
 - ... or upon a large enough change
- Automatic generation of (very basic) overview GUIs for devices (ATK, Synoptic views with JDraw)
- Access control: restrict user access on devices

- Developed principally at ALBA (Barcelona, Spain)
- Aims of the project
 - A further abstraction layer on Tango: controllers and devices
 - Highly flexible and powerful framework for scan measurements
 - Macro server
 - Interactive command line
 - Data recorders: HDF5, SPEC, NeXus
- Sister project: Taurus (<https://taurus-scada.org>)
 - Creation of full-featured GUIs (forms, plots, controls etc) for data acquisition
 - “Configure instead of coding”



The Sardana Architecture

- Two main device servers, each running several device classes
 - **Pool:** list of physical and virtual devices known to Sardana
 - Elements: controllers and their controlled devices
 - **MacroServer:** list of macros (procedures) that can be used
 - Door: a macro running context. Sardana clients (see next slide) connect to these. Each door can run one macro at a time.
- Communication between pool and macroserver objects, as well as clients: over Tango



Spock: the Primary Interface to Sardana

- (Not just) a clone of SPEC
- An extension of IPython
- Macros:
 - IPython “magic commands”
 - Some are familiar from SPEC:
 - mv, umv, mvr, umvr: move motors
 - ascan, dscan: scans (step-wise or continuous, multidimensional also)
 - ct: count for a given time
 - wa, wm, ...: query motor positions
- Extensible in Python:
 - Macros (relatively easy to develop them)
 - Controllers (timers&gates, 0-1-2D counters, multi-axis motor controllers, I/O registers, pseudo counters, pseudo motors)
 - Recorders (usually the out-of-the-box ones are fine: .spec, .hdf5, .nxs)
- Not the only viable method: MacroExecutor GUI (or build your own)

```
IPython: home/labuser
MainThread INFO 2024-09-23 16:01:23,829 TaurusRootLogger: Using PyQt5 (v5.15.9 with Qt 5.15.8 and Python 3.10.14)
Spock 3.5.0 -- An interactive laboratory application.

help -> Spock's help system.
object? -> Details about 'object'. ?object also works, ?? prints more.

IPython profile: spockdoor

Connected to CREDO

CREDO [1]: wa
Current positions (user) on 2024-09-23 16:01:29.889234
User      bsx      bsy      caprot   ph1x     ph1y     ph2x     ph2y
User  3.4587  1.3000  0.0000  -1.3164  5.7350  -0.0915  15.2967
User      ph3x     ph3y      sx       sy
User -0.5599  10.8371  -7.7387  20.2472

CREDO [2]: ?umv
Docstring:
Syntax:
    umv [ <motor> <pos> ]

Move motor(s) to the specified position(s) and update

Parameters:
    motor : (Moveable) Motor to move
    pos   : (Float) Position to move to

Allows hooks:
    pre-move
    post-move

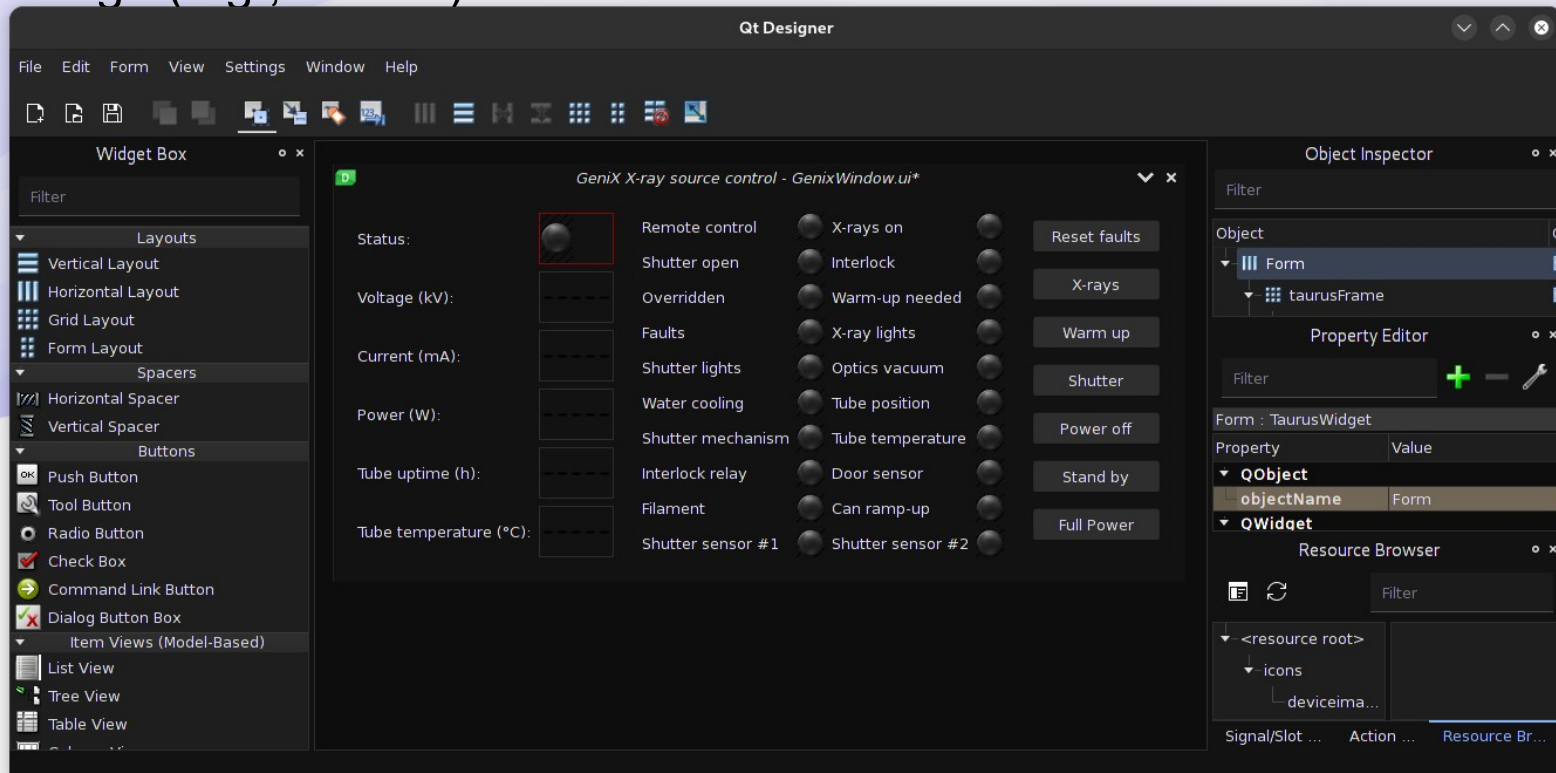
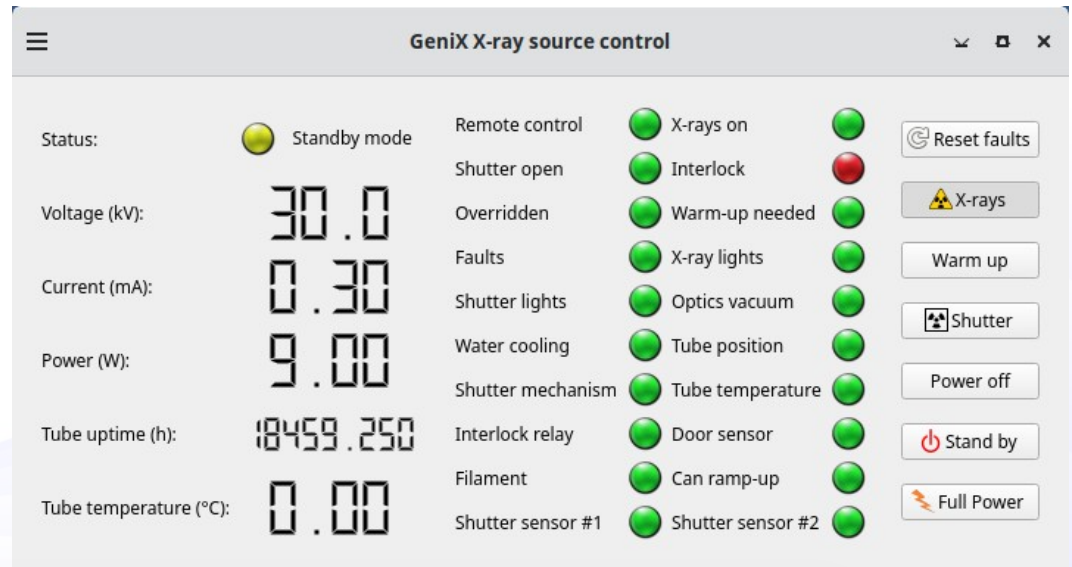
WARNING: do not rely on the file path below
File: /opt/mambaforge/envs/cct/lib/python3.10/site-packages/sardana/spock/spockms.py

CREDO [3]:
```



Taurus: graphical user interface

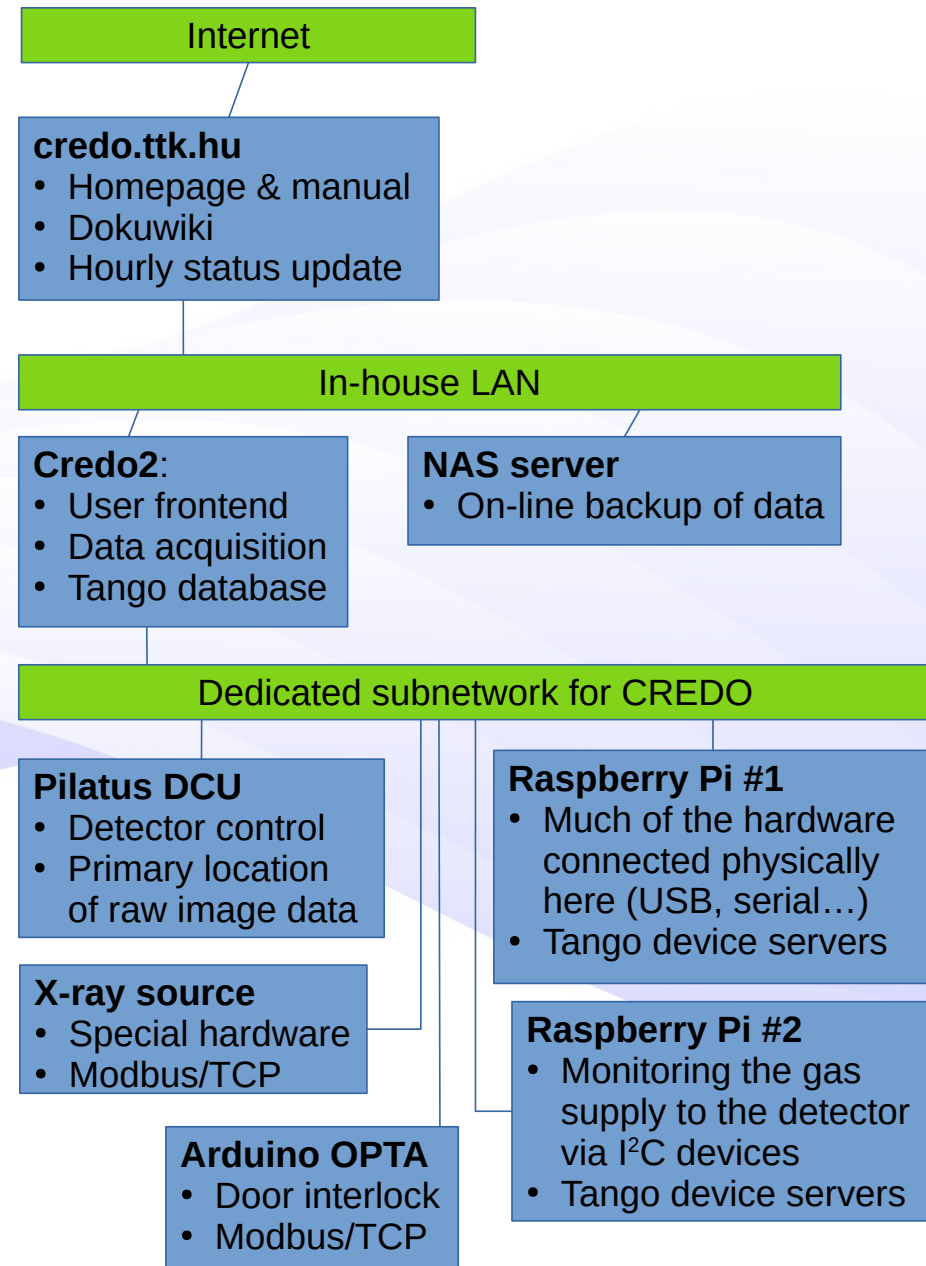
- Based on Qt v5
- Widgets associated to Tango device attributes
 - Automatic polling for changes
 - Instantaneous visualization of device state
 - Control of devices
- Taurus Designer: Qt Designer extended with Taurus widgets
- Might be applicable to others systems beside Tango (e.g., EPICS)



How it is done in reality our lab?

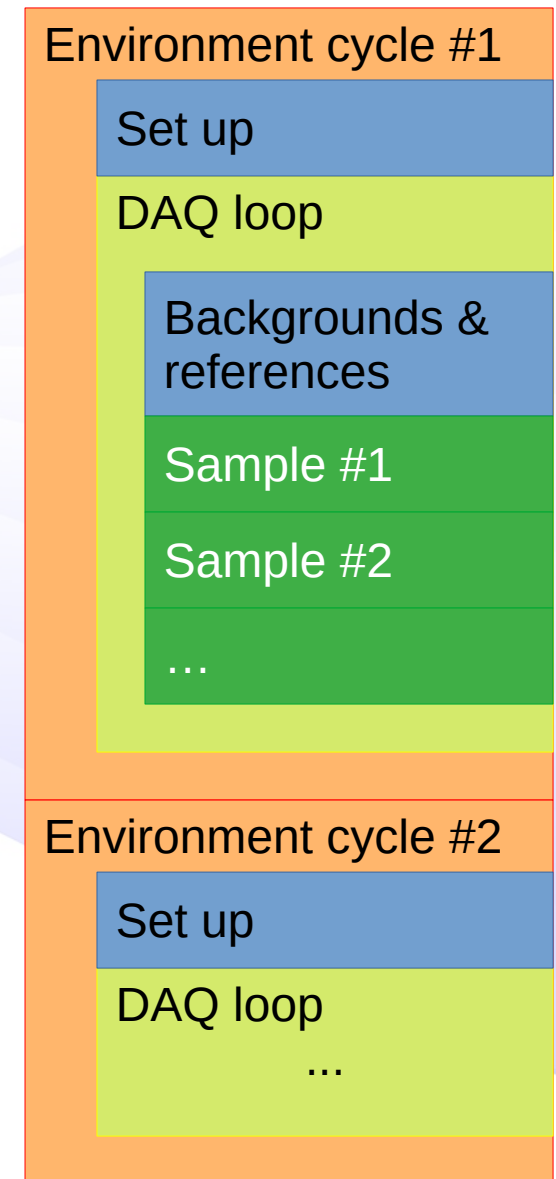
Tango and Sardana in CREDO

- Computers on a dedicated subnet
 - **Credo2**: instrument control, user interface, SQL database, DatabaseDS
 - **Raspberry Pi #1**:
 - RS-232 and USB device connections
 - **Raspberry Pi #2**:
 - I²C devices for detector gas supply monitoring
 - **X-ray source** (Modbus over TCP)
 - **Pilatus-300k DCU**:
 - Dedicated computer, runs `camserver`
 - **Arduino OPTA**
 - door interlock, to be implemented)
- Device servers:
 - Interfaces (SerialLine, Modbus) from the Tango Class Catalogue, mostly on RPi #1
 - Hardware-specific: skeleton made by Pogo, coded with PyTango
 - Software “devices”:
 - Sardana MacroServer and Pool
 - ...



Data Acquisition Routine in CREDO using Tango and Sardana

- **Geometry set-up:** Aperture alignment using *scans*: maximizing beam intensity, minimizing “parasitic scattering”
 - Virtual counters: full detector area sum, ...
- **Finding samples:** motor positions corresponding to individual samples on the motorized sample stage: *scans* again
 - Updating the sample database
- **Transmission measurement:** only once, before data acquisition
- **Data acquisition sequence**
 - Environment cycle: constant *in situ* parameters
 - Data acquisition loop: recording images
 - First measure correction and calibration images
 - Then the samples sequentially
 - “Rinse, repeat”
- At every step: Sardana macros



DAQ Sequence in TOML files

- TOML: Tom's Obvious Minimal Language (<https://toml.io>)
- Human-readable (and editable) syntax
- Less syntactic cruft than JSON
- Can be validated against a schema (semantic check)
 - Required fields
 - Sanity of values (type, range)
- Can be created by a step-by-step GUI wizard or edited by hand

```
# CREDO experiment sequence generated on 2024-07-18 14:36:58.354822
# Run it in Spock with the command
#   saxsseq <absolute path to script file>
```

```
[config]
iterations = 1
# ... omitted for clarity
```

```
[init]
beamstopin = true
xraypower = "full"
closeshutter = true
openshutter = false
```

```
[trim]
energy = 4024 # eV
gain = "highG"
```

```
[finish]
xraypower = "off"
```

```
[references]
dark.name = "Dark"
dark.time = 120.000 # sec
empty.name = "Empty_Beam"
empty.time = 120.000 # sec
absint.name = "Glassy_Carbon"
# ... omitted for clarity
```

```
[[sample]]
name = "DSPC_cho[PEG_1x]"
time = 300.000 #sec
repeats = 6
```

```
[[sample]]
name = "DSPC_cho[PEG_2x]"
time = 300.000 #sec
repeats = 6
```

```
[[cycle]]
iterations = inf
refs = true
samples = true
temperature.set = 25.000
temperature.stabilitycheckradius = 0.100 # °C
temperature.stabilitychecktime = 30.000 # sec
```

	Sample name	Exposure time (sec)
Dark background:	Dark	120.00
Empty beam background:	Empty_Beam	120.00
Intensity normalization:	Glassy_Carbon	120.00
Angular calibration:	AgBeh_SBA15_capillary_20231130	120.00



Additional Concepts – “Misusing” Tango

Additional Concepts – or How to “Misuse” Tango and Sardana

■ Sample database

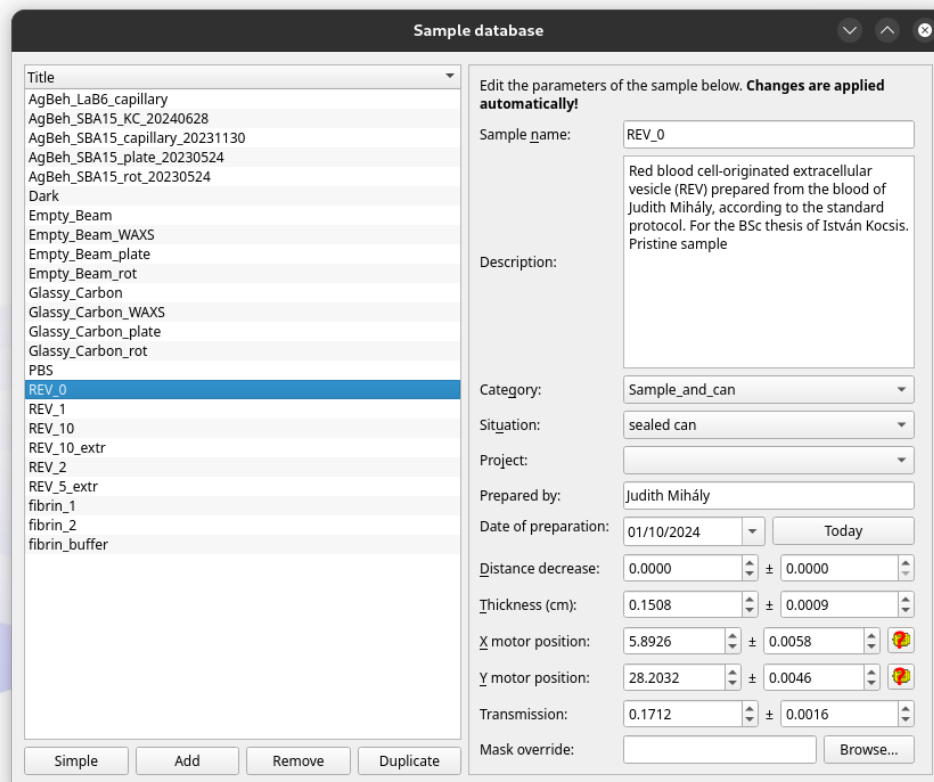
● SQL table

- Short, unique title + longer, free-format description
- Thickness (for absolute intensity calibration)
- Transmission (measured separately)
- X and Y motor positions
- ...

● Managed by: SampleStore Tango device

● Editing and viewing through GUI and with custom Spock macros

● NeXus-ready...

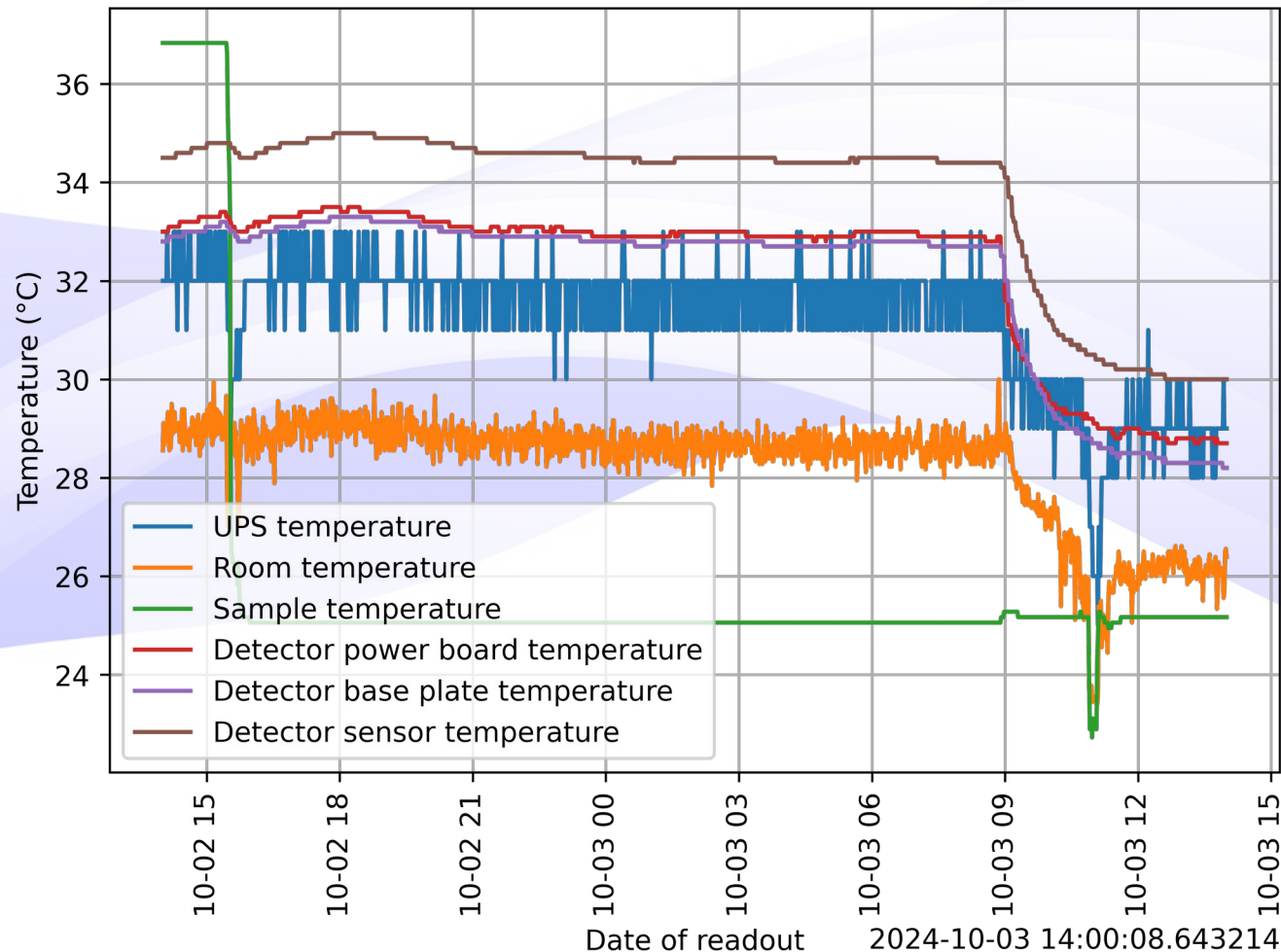


The screenshot shows a window titled "Sample database" with a list of sample titles on the left and a detailed view for the selected sample "REV_0" on the right. The list includes titles like "AgBeh_LaB6_capillary", "AgBeh_SBA15_KC_20240628", "Dark", "Empty_Beam", "Glassy_Carbon", "PBS", "REV_0", "REV_1", "REV_10", "REV_10_extr", "REV_2", "REV_5_extr", "fibrin_1", "fibrin_2", and "fibrin_buffer". The detailed view for "REV_0" includes a description: "Red blood cell-originated extracellular vesicle (REV) prepared from the blood of Judith Mihály, according to the standard protocol. For the BSc thesis of István Kocsis. Pristine sample". Other fields include Category: "Sample_and_can", Situation: "sealed can", Project: "", Prepared by: "Judith Mihály", Date of preparation: "01/10/2024", Distance decrease: "0.0000 ± 0.0000", Thickness (cm): "0.1508 ± 0.0009", X motor position: "5.8926 ± 0.0058", Y motor position: "28.2032 ± 0.0046", Transmission: "0.1712 ± 0.0016", and Mask override: "Browse...". Buttons at the bottom include "Simple", "Add", "Remove", and "Duplicate".

Additional Concepts – or How to “Misuse” Tango and Sardana

■ State logger: Tango Device

- Periodically saving selected attribute values into a SQL database
- Script: hourly run, draw graphs
- Periodically uploaded to the homepage (<https://credo.ttk.hu/status:start>)



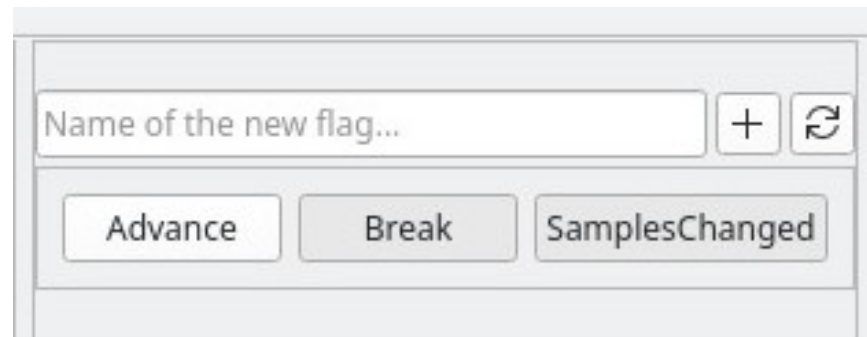
Additional Concepts – or How to “Misuse” Tango and Sardana

■ On-line data reduction pipeline

- Required calibrations and corrections to be performed on each detector image as soon as they are ready
- Implemented as a Tango device
- Processing queue
- Images submitted as soon as ready
- Corrected data saved on disk

■ Flags

- On/off switches
- User interaction into running macros
- E.g., “Break”: stop data acquisition after the current image is done



What's past and what's next?

- Summary:
 - Frameworks developed with large-scale facilities in mind, but can be downscaled to lab-based instruments, too
 - Tango: software bus, distributed object model of real and virtual devices
 - Sardana: macros and procedures (and the needed devices), on Tango grounds
 - Taurus: GUI & abstraction layer (Tango, EPICS, ...)
- Omitted (for now): data storage (See you tomorrow!)
 - How, where, what, why
 - Formats
- Guided tour in the SAXS lab for those interested, after this lecture
- Code available at:
 - <https://gitlab.com/bionano/credo>



Thank you for your attention!

- Research Group for Biological Nanochemistry, HUN-REN Research Centre for Natural Sciences (<https://bionano.ttk.hu/biological-nanochemistry>)
- CREDO SAXS laboratory (<https://credo.ttk.hu>)

